

Safety technique

Standstill monitor LH 5946 SAFEMASTER S



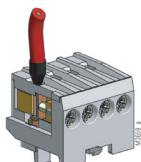
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Options with plugin terminal blocks



LH 5946 P_

Terminal block
with cage clamp terminals
(PC / plugin cageclamp)Terminal block
with screw terminals
(PS / plugin screw)

- TÜV-Approval
 - Safety Integrity Level (SIL) 3 to IEC EN 61508
 - SIL Claimed Level (SIL CL) 3 to EN 62061
 - Performance Level (PL) e to DIN EN ISO 13849-1
 - Safety Category (SK) 4 to EN 954-1
- Safe standstill detection on 3- and single-phase motors
- no external sensors necessary
- independent of direction
- broken wire detection
- positive guided safety contacts:
 - 3 NO contacts, 1 NC contact for AC 250 V
- 2 semiconductor monitoring outputs
- 1 monitoring output (NO contact)
- adjustable voltage setting
- adjustable standstill time delay
- LED indicators for standstill, event of line breakage and operation voltage
- suitable for operation with inverters
- Width 45 mm

Approval and marking



Applications

Safe standstill detection on 3- and single-phase motors, e.g. to enable gate interlocks on machine tools or to activate hold in brakes

Function

The Standstill monitor LH5946 is suitable to monitor the standstill of all electric motors that generate a remanence voltage while coasting to stop. The LH 5946 is connected to the motor terminals and measures the induced back emf voltage. 2 redundant measuring channels are used (L2-L1 and L3 L1). If the back emf voltage drops to 0 simultaneously in both channels this indicates standstill and the output relay is energized.

To adapt the unit to all different types of motors and applications the voltage threshold indicating standstill on LH 5946 is adjustable. Also the time delay between detection and energisation of the relay is adjustable (standstill time t_s).

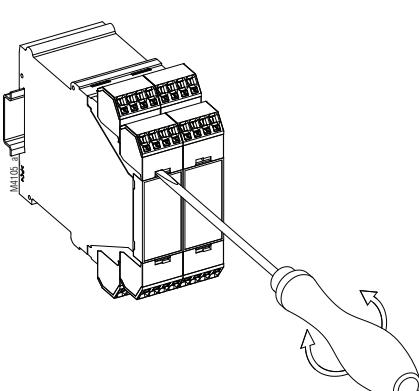
In addition the unit detects broken wire on the measuring inputs L1 / L2 / L3. If broken wire is detected the output relays goes into safe state (as with running motor). This state is stored and can be reset by bridging terminals X3-X2.

The input signals of both channels are permanently compared. If the signals are different for more than 2.5 sec a simultaneity failure is detected. This failure resets when both input channels receive simultaneous signals with a level, above the voltage threshold and hysteresis.

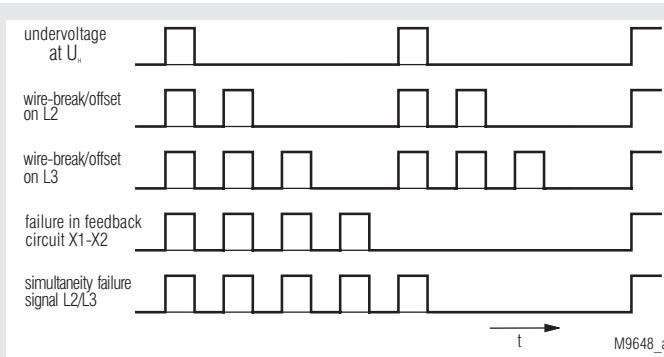
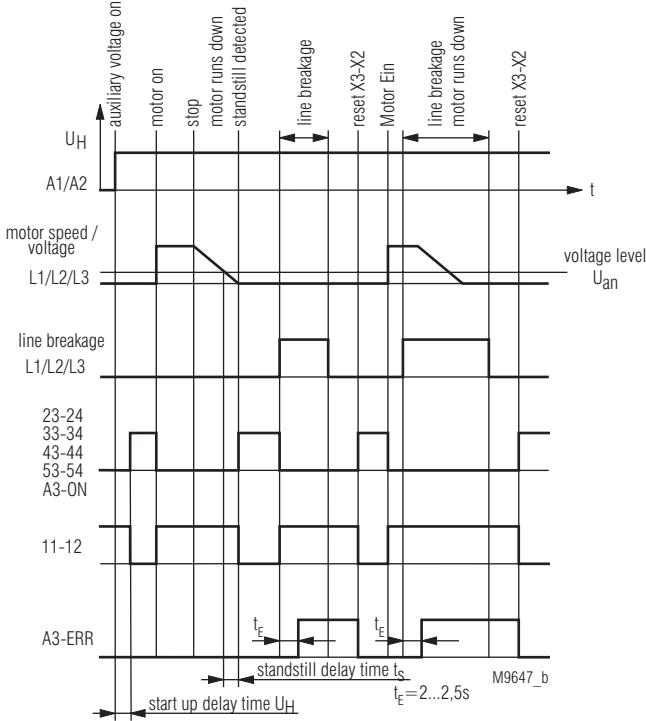
To the terminals X1-X2 the feedback circuit of external contactors (used for contact reinforcement) is connected (NC contact). If no feedback circuit is required, these terminals must be linked. Open terminals will cause a failure message.

Notes

The terminals X1 - X2 - X3 has no galvanic separation to the measuring circuit L1 - L2 - L3. They must be controlled with volt free contacts.

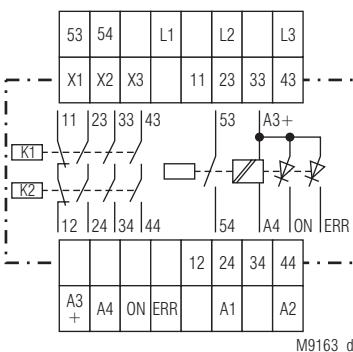


Function diagramm



Flashing codes of the LED „ERR“ in sequence of priority

Circuit diagram



Indicators

- | | |
|-------------------------|--|
| green-red LED „UH“: | green on, when operation
red on, with internal error |
| yellow-green LED „OUT“: | yellow on, at EMK > U_{an}
flashes green at time progression of t_s
permanent on, when output contacts
are enable |
| red LED „ERR“: | flashes at error in measuring and
feedback circuit and low auxiliary
voltage U_H (see flashing codes) |

Technical Data

Input (L1 - L2 - L3)

- Measuring-/Motor voltage:** max. AC 690 V
Input resistance: 500 kΩ
Response value U_{an} : 20 mV ... 400 mV, adjustable or
 0.2 ... 4 V, adjustable

Response value dependent on frequency

Input frequency (Hz):	50	100	200	400	600	1k	1,5 k	2k
Multiplication factor for U_{an} :	1,0	1,1	1,2	1,5	2,0	2,8	5	8

- Hysteresis (for detection of running motor):** 100 %
Release delay for detection of running motor: < 100 ms

- Standstill time delay t_s :** 0.2 ... 6 s adjustable

- Auxiliary voltage U_H (A1 - A2):** AC 115 V, AC 230 V, AC 400 V, DC 24 V
Recommended fusing: 2 A

Voltage range

- AC: 0.8 ... 1.1 U_N
 DC: 0.9 ... 1.2 U_N

- Nominal consumption:** 5 VA, 3 W

- Nominal frequency (AC):** 50 / 60 Hz

- Frequency range (AC):** 45 ... 65 Hz

- max. residual ripple (DC):** 10 %

- Start up delay when connecting U_H at standstill:** 0,4 ... 0,8 s + adjustable t_s

Output

Contacts (safety contacts)

- LH 5946.48: 3 NO contacts, 1 NC contact

- Contact type:** relay, positive guide

- Nominal output voltage:** AC 250 V

- Thermal current I_{th} :** 5 A (bis 40°C)

- Quadratic total current:** see derating curve

- Switching capacity**

- to AC 15

- NO contact:

- NC contact:

- to DC 13:

Fusing of the safety contacts:

- max. fuse rating 4AgL
 line circuit breaker C6A

- 1200 / h

- AC 3 A / 230 V IEC/EN 60 947-5-1
 AC 2 A / 230 V IEC/EN 60 947-5-1
 DC 2 A / 24 V IEC/EN 60 947-5-1

- Max. operating frequency:** max. fuse rating 4AgL

- Contact service life:** line circuit breaker C6A

- at AC 230 V / 5 A cosφ = 0.5: 1200 / h

- Mechanical life:** ≥ 2 × 10⁵ switching cycles

Semiconductor monitoring output:

- 100 mA DC 24 V, plus switching,
 galvanic separation; supply via
 A3+ / A4 for output; „ON“ and „ERR“

- NO monitoring contact:** 3 A AC 250 V (closed when enabled)

Technical Data

General Data

Nominal operating mode:	continuous operation
Temperature range	
operation:	- 25 ... + 60°C (+ 40°C with max. contact current, see Derating)
storage:	- 40 ... + 75°C
Clearance and creepage distance	
rated impuls voltage / pollution degree:	IEC 60 664-1
Contacts 11/12, 23/24, 33/34, 43/44 against all others:	6 kV / 2
Contacts 11/12, 23/24, 33/34, 43/44 against each others:	4 kV / 2
Indicator contact 53/54 against all others:	4 kV / 2
Semiconductor outputs A3+/ ON / ERR / A4 against all others:	6 kV / 2
Auxiliary voltage A1 / A2 against all others	
at auxiliary voltage AC:	6 kV / 2
at auxiliary voltage DC:	4 kV / 2
Control terminal X1 / X2 / X3:	no galvanic separation to L1 / L2 / L3
EMC	
Electrostatic discharge (ESD):	8 kV (air) IEC/EN 61 000-4-2
HF irradiation:	20 V/m IEC/EN 61 000-4-3
Fast transients:	2 kV IEC/EN 61 000-4-4
surge voltage between	
measuring input L1 / L2 / L3:	2 kV IEC/EN 61 000-4-5
wires for power supply A1 / A2	
at AC - U _H :	2 kV
at DC 24 V:	1 kV IEC/EN 61 000-4-5
HF-wire guided:	10 V IEC/EN 61 000-4-6
Interference suppression:	limit value class B EN 55 011
Degree of protection	
Housing:	IP 40 IEC/EN 60 529
Terminals:	IP 20 IEC/EN 60 529
Enclosure:	thermoplastic with VO behaviour according to UL subject 94 amplitude 0.35 mm
Vibration resistance:	frequency 10 ... 55 Hz, IEC/EN 60 068-2-6
Climate resistance:	25 / 060 / 04 IEC/EN 60 068-1
Terminal designation:	EN 50 005 DIN 46 228-1/-2/-3/-4
Wire connection	60°C Copper conductors only
UL detail:	
Screw terminals (integrated):	1 x 4 mm ² solid or 1 x 2.5 mm ² stranded ferruled or 2 x 1.5 mm ² stranded ferruled or 2 x 2.5 mm ² solid
Insulation of wires or sleeve length:	8 mm
Plugin with screw terminals	
max. cross section for connection:	1 x 2.5 mm ² solid or 1 x 2.5 mm ² stranded ferruled
Insulation of wires or sleeve length:	8 mm
Plugin with cage clamp terminals	
max. cross section for connection:	1 x 4 mm ² solid or 1 x 2.5 mm ² stranded ferruled
min. cross section for connection:	0.5 mm ²
Insulation of wires or sleeve length:	12 ^{±0.5} mm
Wire fixing:	Plus-minus terminal screws M 3.5 box terminals with wire protection or cage clamp terminals
Mounting:	DIN-rail IEC/EN 60 715
Weight:	approx. 400 g
Dimensions	
Width x height x depth:	45 x 90 x 121 mm

Technical Data

Safety related data

Values according to EN ISO 13849-1:		
Category:	4	
PL:	e	
MTTF _d :	93	a
DC _{avg} :	99,0	%
d _{op} :	365	d/a (days/year)
h _{op} :	24	h/d (hours/day)
t _{Zyklus} :	28,8E+03	s/Zyklus
≥ 1	/8 h	(hours)

Values according to IEC EN 62061 / IEC EN 61508:

SIL CL:	3	IEC EN 62061
SIL:	3	IEC EN 61508
HFT ¹⁾ :	1	
DC _{avg} :	99,0	%
SFF:	99,7	%
PFH _D :	4,10E-10	h ⁻¹

¹⁾ HFT = Hardware-Failure Toleranz



The values stated above are valid for the standard type.
Safety data for other variants are available on request.

The safety relevant data of the complete system has to be determined by the manufacturer of the system.

UL-Data

The safety functions were not evaluated by UL. Listing is accomplished according to requirements of Standard UL 508, "general use applications"

Measuring-/Motor voltage: max. AC 600 V

Ambient temperature: - 25 ... + 60°C, (+ 40°C with max. contact current, see Derating)

Switching capacity

safety contacts
(11/12, 23/24, 33/34, 43/44)

Ambient temperature 40°C: Pilot duty B300
5A 250Vac G.P.
5A 24Vdc G.P.

Ambient temperature 60°C: Pilot duty B300
2A 250Vac G.P.
2A 24Vdc G.P.

Switching capacity

indicator contact
(53/54)

Pilot duty B300
3A 250Vac G.P.

Wire connection: 60°C / 75°C copper conductors only
Fixed screw terminal: 1 x AWG 20 - 12 Sol/Str Torque 0.8 Nm or
2 x AWG 20 - 14 Sol/Str Torque 0.8 Nm

Plugin screw terminal: AWG 20 - 14 Sol Torque 0.8 Nm or
AWG 20 - 18 Str Torque 0.8 Nm

Plugin cage clamp terminal: AWG 20 - 12 Sol/Str

Technical data that is not stated in the UL-Data, can be found in the technical data section.

Standard type

LH 5946.48/61 DC 24 V

Article number:

0059266

3 NO contacts, 1 NC contact

DC 24 V

Auxiliary voltage U_H :

20 ... 400 mV

Response value U_{an} :

0.2 ... 6 s

Standstill time t_s :

0.2 ... 6 s

1 semiconductor and 1 NO contact for indicator output

1 semiconductor for fault indicator output

Width: 45 mm

Order example

LH 5946.48 - 61 DC 24 V 20 ... 400 mV 0.2 ... 6 s

Standstill time t_s

Response value U_{an}

Auxiliary voltage U_H

UL-approval

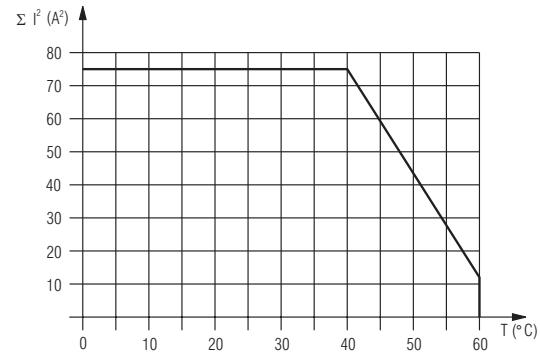
Type of terminals without indication:
terminal blocks fixed,
with screw terminals

PC (plugin cage clamp)
pluggable terminal blocks
with cage clamp terminals

PS (plugin screw)
pluggable terminal blocks
with screw terminals

Type

Characteristic



M9658

Quadratic total current

$$\Sigma = I_1^2 + I_2^2 + I_3^2$$

I_1, I_2, I_3 - current in contact paths

max. permitted current up to 40°C on 3 contact paths = 5A

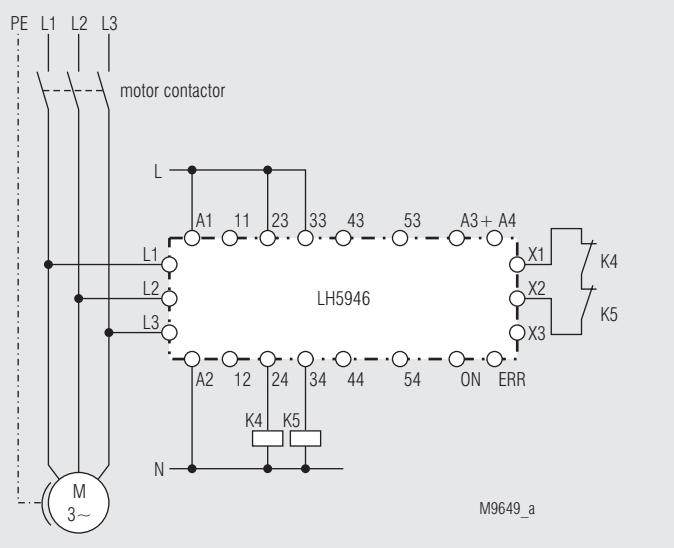
$$(5^2 + 5^2 + 5^2 = 75 \text{ A}^2)$$

max. permitted current up to 60°C on 3 contact paths = 2A

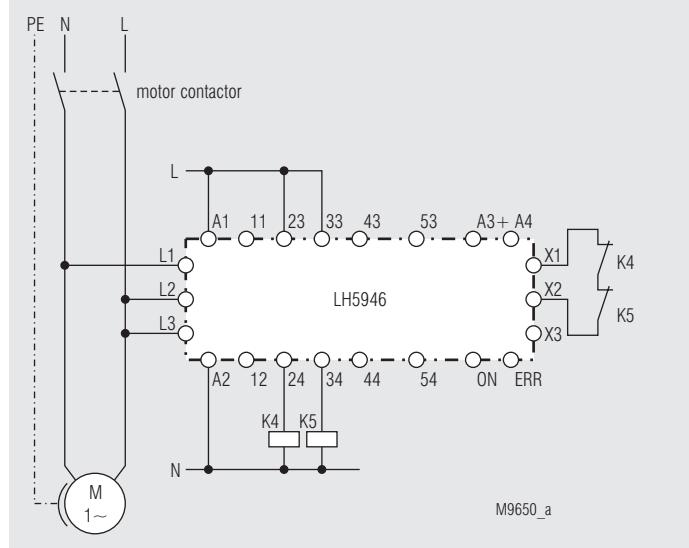
$$(2^2 + 2^2 + 2^2 = 12 \text{ A}^2)$$

Derating curve for contact currents of safety contacts

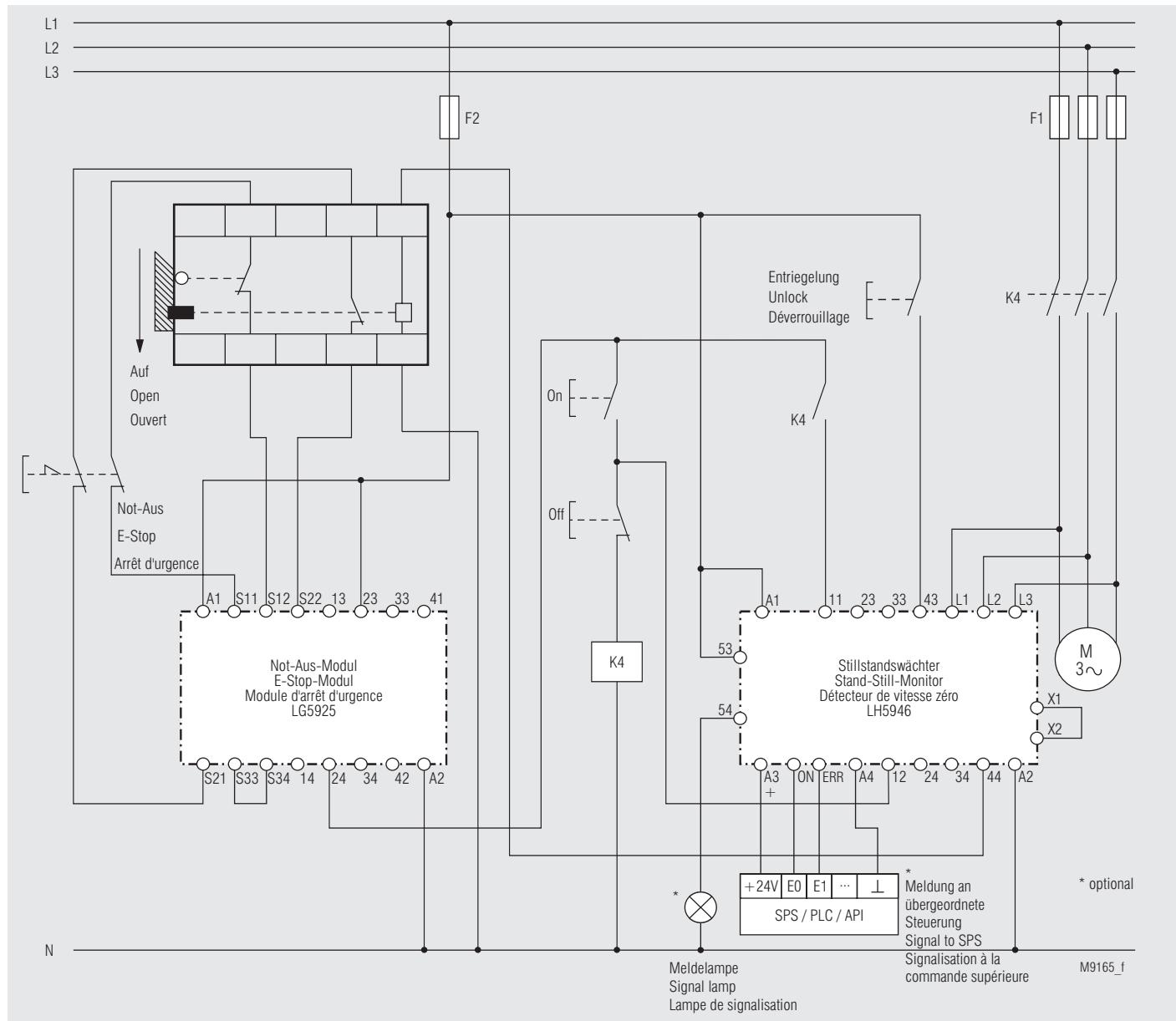
Application example



With 3-phase motor

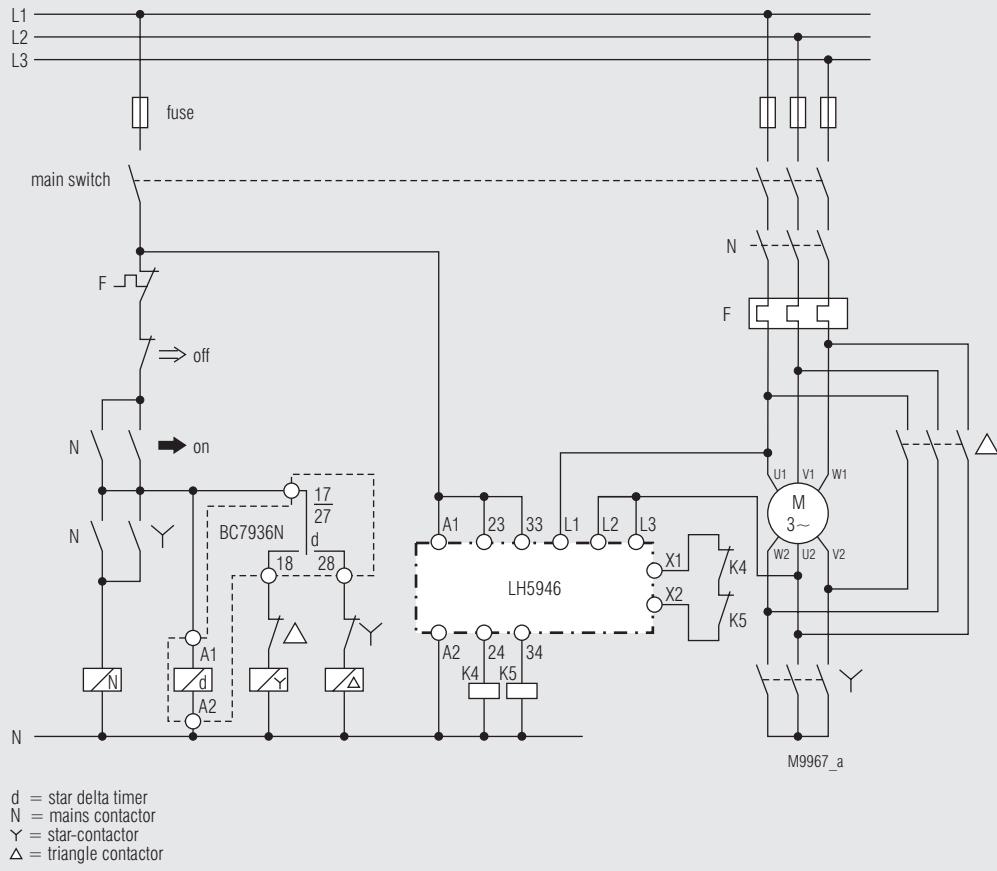


With single-phase motor

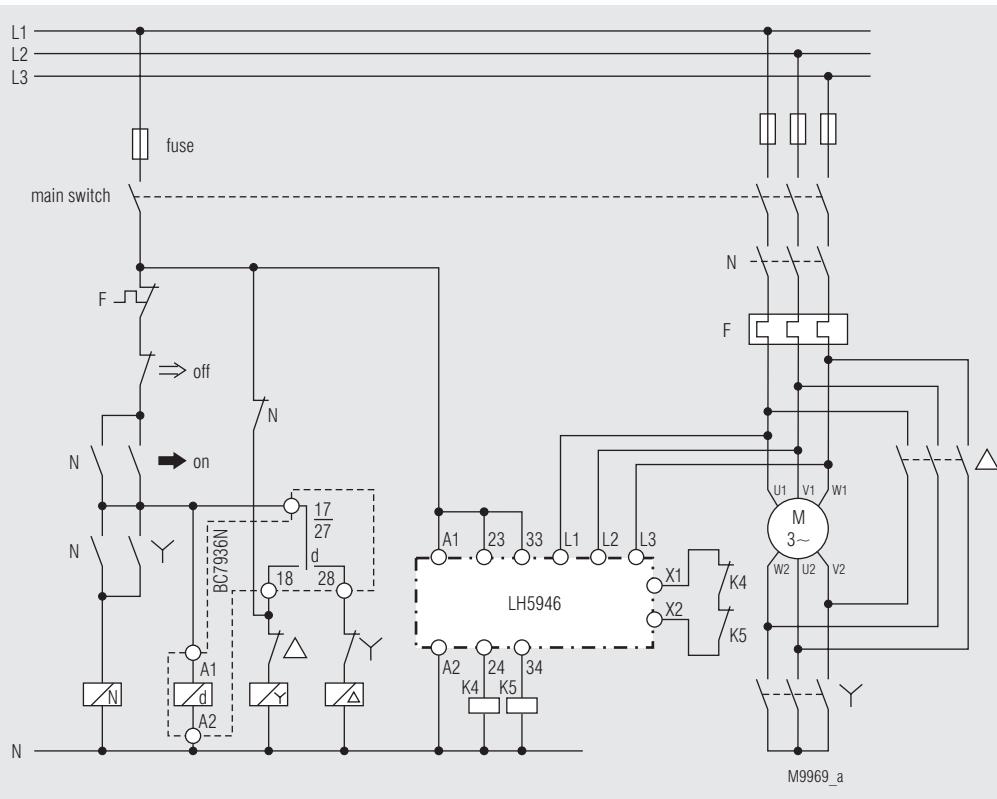


Typical connection combination with E-Stop

Application example



Typical connection combination with star delta timer



d = star delta timer
 N = mains contactor
 Y = star-contactor
 Δ = triangle contactor

With "3-phase" connection of LH5946 the star contactor (Y) has to be closed after the motor is switched off to detect standstill. If this is not the case the failure signal "broken wire" blocks the output contacts in off position.

Typical connection combination with star delta timer