4/4-way servo solenoid directional control valves, directly operated, with electrical position feedback and on-board electronics (OBE)

RE 29035/10.10 1/12 Replaces: 05.10

Type 4WRPEH6

Size 6 Unit series 2X Maximum working pressure P, A, B 315 bar, T 250 bar Nominal flow 2...40 l/min (Δp 70 bar)



Type 4WRPEH6

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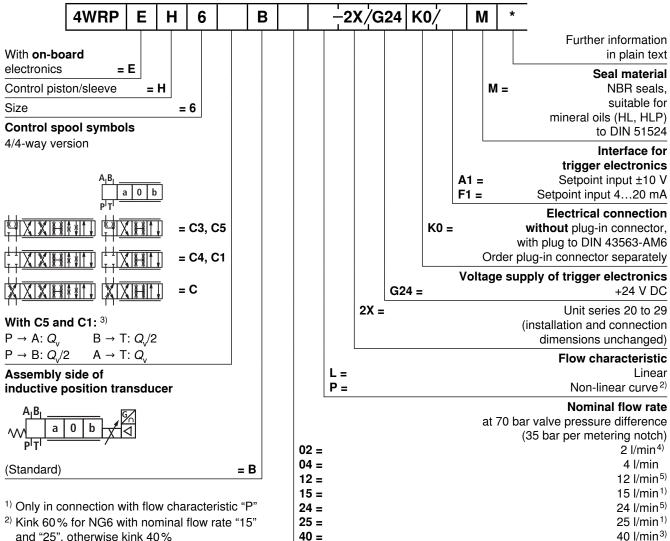
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Features

- Directly operated servo solenoid directional control valve, with control piston and sleeve in servo quality
- Actuated on one side, 4/4 fail-safe position when switched off
- Electrical position feedback and on-board electronics (OBE), calibrated at the factory
- Electrical connection 6P+PE Signal input differential amplifier with interface A1 \pm 10 V or interface F1 4...20 mA (Rsh = 200 Ω)
- Used in electrohydraulic controllers in production and testing systems

For information regarding the available spare parts see: www.boschrexroth.com/spc

Ordering data



and "25", otherwise kink 40%

³⁾ Q_v 2:1 only with nominal flow rate = 40 l/min

⁴⁾ Not in connection with flow characteristic "P"

⁵⁾ Only in connection with flow characteristic "L"

Function, sectional diagram

General

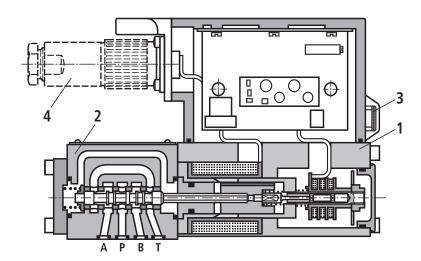
In the field of integrated electronics, the specified command value is compared with the actual position value. In case of deviations from the standard, the lifting solenoid is activated. Due to the changed magnetic force, the lifting solenoid adjusts the control valve against the spring.

Lifting/control cross-section are adjusted proportionally to the command value. In case of a command value provision of 0 V, the electronics adjusts the control valve against the spring to center position. In deactivated condition, the spring is unloaded to a maximum and the valve is in fail-safe position.

Switch-off behavior

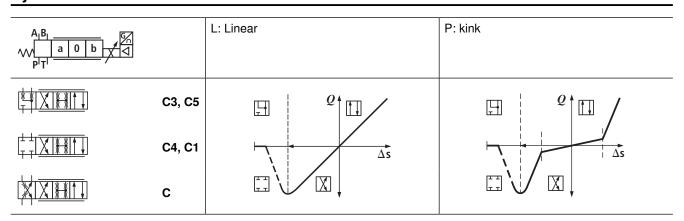
If the electronics is switched off, the valve immediately moves to the secured basic position (fail safe).

In this process, the P-B/A-T position is passed which might cause movements at the controlled component. This must be taken into account when designing the plant.



- 1 Control solenoid with position transducer
- 2 Valve body
- 3 Plug for possible 2nd stage
- 4 Plug in connector

Symbols



Testing and service equipment

- Service case type VT-VETSY-1 with test device, see data sheet 29685
- Measuring adapter 6P+PE type VT-PA-2, see data sheet 30068

Technical data

General										
Construction				Spool-type valve, directly operated, with steel sleeve						
Actuation				Control solenoid with position control, OBE						
				Subplate, mounting hole configuration (ISO 4401-03-02-0-05)						
Type of mounting Installation position				Optional						
· · · · · · · · · · · · · · · · · · ·				<u> </u>						
Ambient temperature range °C				-20+50						
Weight kg				2.7 Max. 25 <i>g</i> , shaken in 3 dimensions (24 h)						
Vibration resistance					, snaken in	1 3 aimensioi	ns (24 n)			
Hydraulic (measured with HLP 46, $\vartheta_{oil} = 40^{\circ}$				· · · · · · · · · · · · · · · · · · ·						
Pressure fluid				Hydraulic oil to DIN 51524535, other fluids after prior consultation						
Viscosity range	reco	recommended m		20100						
	max. permitted mm ²			10800						
Pressure fluid temperature range °C				-20+70						
Maximum permissib	le degree o	f								
	contamination of pressure fluid									
Purity class to ISO 4406 (c)				Class 18/16/13 1)						
Direction of flow	Direction of flow				See symbol					
Nominal flow										
at $\Delta p = 35$ bar per n	otch ²⁾		l/min	2	4	12	15	24	40	
Max. working	Ports P, A	., В	bar	315				·		
pressure	Port T		bar	250						
Operating limits at Δ	.p									
Pressure drop at val		C, C3, C5	bar	315	315	315	315	315	160	
Q_{Vnom} : > Q_{N} valves		C4, C1	bar	315	315	315	280	250	100	
Max. recommended Linear characteristic										
nominal flow	curve L		cm ³ /min	<150	< 180	<300	_	< 500	<900	
at 100 bar	Inflected of	charac-								
	teristic curve P		cm ³ /min	_	_	_	<180	<300	<450	
Fail-safe position				T	T		1			
-	C Flow at $\Delta p = 35$ bar per notch I/mir									
	Flow at $\Delta p = 35$ bar per notch			2	4	10	13	18	20	
	C3, C5 $\frac{\text{cm}^3/\text{min}}{\text{min}}$			50 P-A						
Zero flow at 100 bar cm ³ /min			70 P–B							
C3, C5l/min_			1020 A-T							
Flow at $\Delta p = 35$ bar per notch I/min			720 B-T							
C4, C1 cm ³ /min			50 P-A							
Zero flow at 100 bar $ \frac{\text{cm}^3/\text{min}}{\text{cm}^3/\text{min}} $			70 P-B							
			70 A-T							
			cm ³ /min	50 B-T						
Fail-safe position reached 0 bar 100 bar			7 ms							
				10 ms						
Static/Dynamic				1						
Hysteresis %				≦0.2						
Manufacturing tolerance for Q_{max} %				<10						
- max				≤10 ≤10						
Response time for signal change 0100 % ms Thermal drift										
				Zero point displacement <1% at ΔT = 40 °C						
Zero adjustment				Factory-set ±1%						

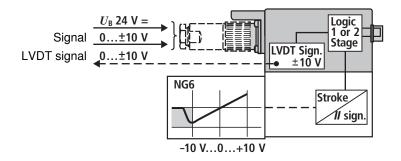
¹⁾ The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see www.boschrexroth.com/filter.

²⁾ Flow rate at a different Δp $Q_{\rm x} = Q_{\rm nom} \cdot \sqrt{\frac{\Delta p_{\rm x}}{35}}$

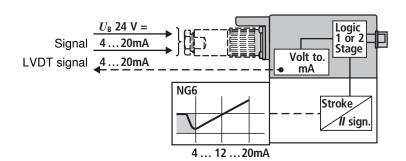
Technical data

Cyclic duration factor %	100				
Degree of protection	IP 65 to EN 60529 and IEC 14434/5				
Connection	Plug-in connector 6P+PE, DIN 43563				
Power supply	24 V DC _{nom}				
Terminal A:	Min. 21 V DC/max. 40 V DC				
Terminal B: 0 V	Ripple max. 2 V DC				
Max. power consumption	40 VA				
External fuse	2.5 A _F				
Input, version A1	Differential amplifier, $R_i = 100 \text{ k}\Omega$				
Terminal D: $U_{\rm F}$	0±10 V				
Terminal E:	0 V				
Input, version F1	Burden, R sh = 200 Ω				
Terminal D: I _{D-E}	4(12)20 mA				
Terminal E: I _{D-E}	Current loop I _{D-E} feedback				
Max. differential input voltage	D → B]				
at 0 V	$\begin{bmatrix} D \rightarrow B \\ E \rightarrow B \end{bmatrix}$ max. 18 V=				
Test signal, version A1	LVDT				
Terminal F: U _{Test}	0+10 V				
Terminal C:	Reference 0 V				
Test signal, version F1	LVDT signal 420 mA at external load 200500 Ω max.				
Terminal F: I _{F-C}	420 mA output				
Terminal C: I_{F-C}	Current loop I_{F-C} feedback				
Protective conductor and screen	See pin assignment (CE-compliant installation)				
Calibration	Calibrated at the factory, see characteristic curve of the valve				
Electromagnetic compatibility	EN 61000-6-2: 2005-08				
tested according to	EN 61000-6-3: 2007-01				



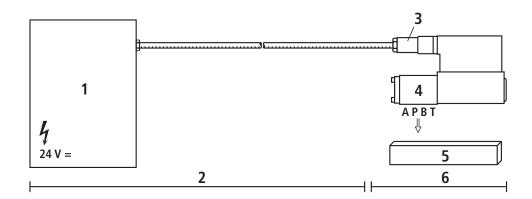


Version F1: mA signal



Electric connection

For electrical data, see page 5



- 1 Control
- 2 Provided by customer
- 3 Plug-in connector
- 4 Valve
- 5 Connecting surface
- 6 Provided by Rexroth

Technical notes on the cable

Version: - Multi-wire cable

> - Extra-finely stranded wire to VDE 0295, Class 6

- Protective conductor, green/yellow

- Cu braided screen

- e.g. Ölflex-FD 855 CP Types:

(from Lappkabel company)

No. of wires: - Determined by type of valve,

plug types and signal assignment

Cable Ø: - 0.75 mm² to 20 m length

1.0 mm² to 40 m length

Outside Ø: - 9.4...11.8 mm - Pg11

12.7...13.5 mm - Pg16

Note

Voltage supply 24 V $\rm DC_{nom}$, if voltage drops below 18 V DC, rapid shutdown resembling

"Enable OFF" takes place internally.

In addition, with F1 version:

 $I_{D-E} \ge 3 \text{ mA} - \text{valve is active}$

 $I_{D-E} \le 2 \text{ mA} - \text{valve is deactivated.}$

Electrical signals emitted via the trigger electronics

(e.g. actual values) must not be used to shut down safety-

relevant machine functions! (See European Standard,

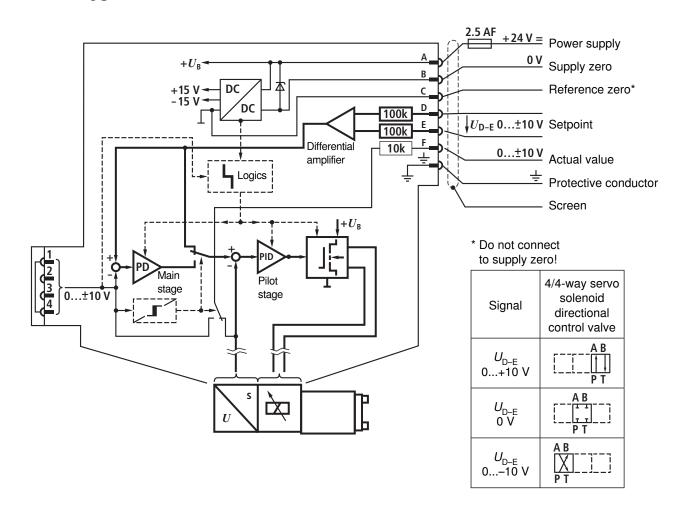
"Technical Safety Requirements for Fluid-Powered Systems

and Components - Hydraulics", EN 982.)

On-board electronics

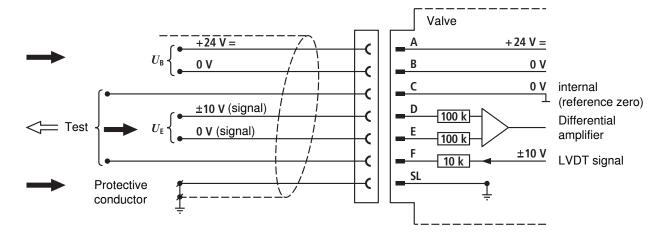
Block diagram/pin assignment

Version A1: $U_{\rm D-E} \pm 10 \text{ V}$



Pin assignment 6P+PE

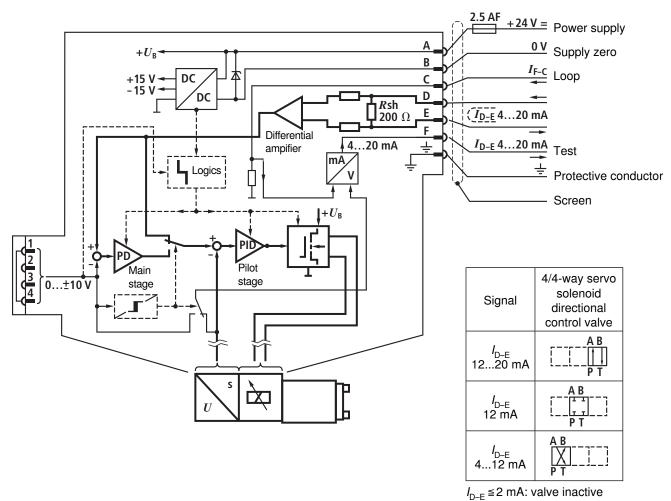
Version A1: $U_{D-E} \pm 10 \text{ V}$ ($R_i = 100 \text{ k}\Omega$)



On-board electronics

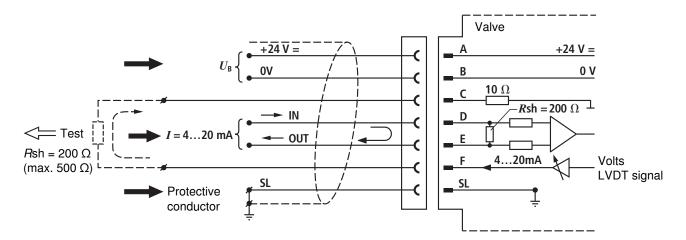
Block diagram/pin assignment

Version F1: I_{D-E} 4...12...20 mA



Pin assignment 6P+PE

Version F1: $I_{\rm D-E}$ 4...12...20 mA (Rsh = 200 Ω)



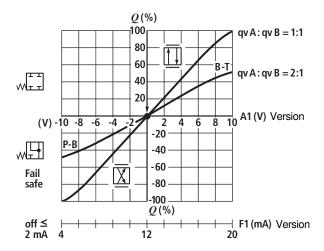
Characteristic curves (measured with HLP 46, ϑ_{oil} = 40 °C ±5 °C)

Flow rate - signal function

 $\begin{aligned} Q &= \mathsf{f} \; (U_{\mathsf{D}-\mathsf{E}}) \\ Q &= \mathsf{f} \; (I_{\mathsf{D}-\mathsf{E}}) \end{aligned}$

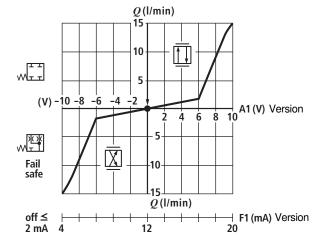
Flow characteristic

L: Linear



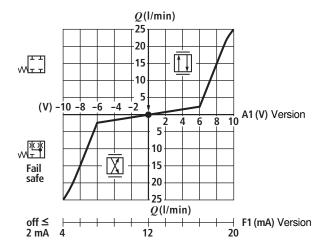
Flow characteristic

P: (kink 60%) 15 l/min

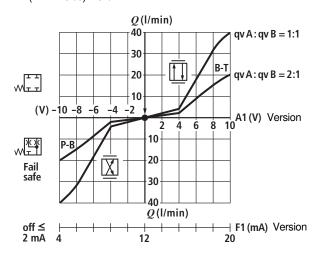


Flow characteristic

P: (kink 60%) 25 l/min

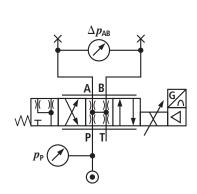


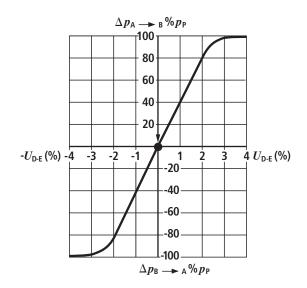
Flow characteristic P: (kink 40%) 40 l/min



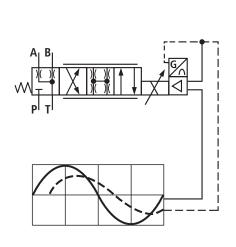
Characteristic curves (measured with HLP 46, ϑ_{oil} = 40 °C ±5 °C)

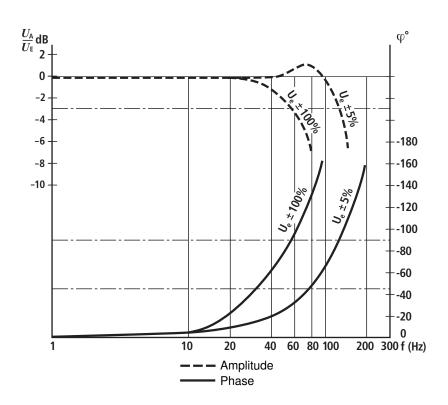
Pressure gain



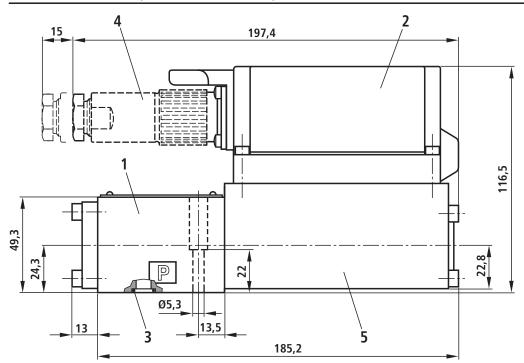


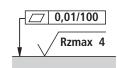
Bode diagram



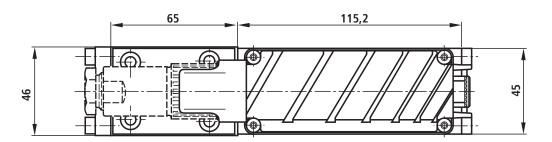


Unit dimensions (dimensions in mm)





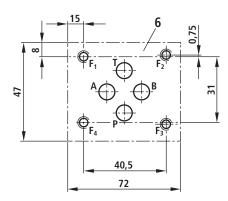
Required surface quality of valve mounting face



- 1 Valve housing
- 2 On-board electronics
- 3 O-rings Ø 9.25 x 1.78 (ports P, A, B, T)
- 4 Plug-in connector not included in scope of delivery, see data sheet 08008 (order separately)
- 5 Control solenoid with position transducer
- 6 Machined valve contact surface, mounting hole configuration to ISO 4401-03-02-0-05 Deviates from standard:
 Ports P, A, B, T Ø 8 mm

Minimum thread depth: Ferrous metal 1.5 x \varnothing Non-ferrous 2 x \varnothing

Subplates, see data sheet 45053 (order separately)



Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

4 cheese-head bolts ISO 4762-M5x30-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F82170)

Tightening torque $M_{\Delta} = 6 + 2 \text{ Nm}$

Material no. 2910151166

or

4 cheese-head bolts ISO 4762-M5x30-10.9

(coefficient of friction $\mu_{\rm total}$ = 0.12–0.17) Tightening torque $M_{\rm A}$ = 8.9 Nm ±10 %

Notes

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